Timber Screw Connection: Study of the Strain along the Interface Using Optical Measurement Techniques and Simulations

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In various engineering applications, self-tapping screws are used to connect timber members. To describe their load-deformation relationship, a better understanding of the strain along the mechanical interface (i.e., timber-screw interface) is required. With a focus on the axial loading of self-tapping screws, only a few studies have dealt with the determination of the strain based on optical measurement techniques. Therefore, in the present study, the strain distribution at the timber-screw interface was monitored during pull-out tests using an optical measurement technique, called electronic speckle pattern interferometry (ESPI). Strains obtained from the ESPI measurements were compared with the results obtained from structural simulations conducted with finite element modelling (FEM). Three different types of solid spruce wood (Picea abies (L.) Karst.) specimens with different grain orientations connected with self-tapping screws (thread length $l_g = 130$ mm, outer thread diameter d = 12 mm) were tested in withdrawal. There was a good agreement between the ESPI and FEM results, confirming that ESPI was a suitable measurement technique. The study also provided insights and results regarding the region of strain concentrations across the length of self-tapping screws.

Keywords: Electronic speckle pattern interferometry; Finite-element modelling; Norway spruce; Optical measurement technique; Pull-out test; Self-tapping screw; Solid timber; Strain measurement

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INTRODUCTION

At the beginning of the automotive industry, timber was commonly used as loadbearing components in vehicles (Braess and Seiffert 2013). In the following decades, timber was replaced by metals, due to the growth of the steel industry. However, ongoing research projects like "Wood C. A. R.", "For(s)tschritt", and the "NCV – Project" focus on the reintroduction of timber and timber composites as structural elements in vehicles again (Kohl *et al.* 2016; Müller *et al.* 2019). One of the reasons for these initiatives is that the use of novel multi-layer materials (*e.g.*, sandwich structures) that contain timber has the potential to significantly reduce weight and therefore decrease the energy consumption of vehicles. To connect timber elements with the surrounding vehicle parts, the use of selftapping screws is an economical and reliable mechanical fastening solution. The main

advantages of self-tapping screws compared to pins, threaded rods, and bolts, are the ease of installation (no pre-drilling is needed) and the possibility to use them in other applications such as tensile joints, butt joints, etc. (Trautz and Koj 2009; Dietsch and Brandner 2015; Ringhofer 2017). Still, mechanically stable and durable bonds of selftapping screws joined with timber are needed to guarantee the safety requirements for their applications. Especially for predominantly axially loaded screws, the stress-strain distribution around the timber-screw joint area is related to the withdrawal behavior of the screw. Therefore, it is important to investigate the strain distribution of such embedded screws, which are loaded axially by applying non-contact measurement techniques. In particular, the observed deformations and strains are essential features for developing a better understanding of the axial withdrawal failure mode of the timber-screw connection. Currently, the estimation of the withdrawal capacity, $F_{ax, \alpha, Rk}$ is obtained from simple, empirical regression models, as recommended in Eurocode 5 of EN 1995-1-1 (2015) for the design of screwed connections in timber structures. The fitting parameters in these models are continuously adjusted and determined due to stochastic-empirical investigations (Wilkinson and Laatsch 1970; Eckelman 1975; Gustafsson et al. 2001; Frese et al. 2010; Jensen et al. 2011; Ringhofer et al. 2015; Percin 2016; Brandner et al. 2019; Du et al. 2019). This is expensive and time-consuming. Moreover, these investigations did not provide a sufficient structural understanding of the mechanics happening at the timberscrew interface.

The estimation of the withdrawal capacity using computer-based numerical investigations, such as finite element modelling (FEM), is another approach, which is scarcely described in the literature. On the one hand, applying FEM for the estimation of the withdrawal capacity of timber-screw connections is highly complex, because of the morphological changes in the wood (densified and damaged wood cell) around the vicinity of the screw, which is difficult to predict and to describe properly. In contrast, FEM also demands experimental results to verify the numerical simulations (Fueyo *et al.* 2009; Steilner 2014; Hochreiner *et al.* 2016; Füssl *et al.* 2017). Electronic speckle pattern interferometry (ESPI), for instance, provides full-field optical strain data with a high-measurement resolution that can be used to capture close-up strain maps along the mechanical timber-screw interface. Results from these types of experiments are essential for analyses and validation purposes when FEM is performed.

Ellingsbø and Malo (2012), Ayoubi and Trautz (2013), Ayoubi (2014), and Trautz (2017) established strain distribution around self-tapping screws joined with timber using a full-field optical gauging technique, namely digital image correlation (DIC) during screw pull-out tests. The DIC can provide full-field visualized strain data that considers a high accurate field of view (FoV) as required to monitor the timber-screw interface. Ayoubi and Trautz (2013) found good correlation of the DIC results compared to the measurements conducted with surface-bonded resistive strain gauges, and the experiments measured with local linear variable differential transformers (LVDT). Nevertheless, in all these research studies, the strain distribution of the outer timber-specimen surface was observed, whereas the screw was embedded in the core of the timber. That means that the screws were surrounded completely by the timber element, which meant that the timber-screw interface could not be closely monitored with the consequence that the strains at the interface were assumed without having direct measurements results. Therefore, the aim of this study was to capture the strains along and close to the timber-screw interface, subject to axial loading. A pull-out experiment was designed to allow direct strain measurements along the interface using the full-field optical gauging technique, ESPI. Previous studies have shown that ESPI

is suitable to measure strain distribution of highly heterogeneous and anisotropic materials like wood in the micro- or nano-scale (Eberhardsteiner 1995; Valla *et al.* 2011; Kumpenza *et al.* 2018).

The hypothesis of this study was that high resolution full-field optical gauging techniques can give insights into the strain distribution along the mechanical timber-screw interface. It was believed that the experimental results of this research study can be used for future screw developments and for validation purposes of computer-based numerical simulations. For that reason, the ESPI measurements were analyzed and compared with established and validated simulation results.

EXPERIMENTAL

Materials

Test-samples

The material used for the specimens was Norway spruce (*Picea abies* (L.) Karst.) (sourced from J. u. A. Frischeis GmbH, Stockerau, Austria). Randomly selected timber logs were processed by means of a circular saw and a planning machine. After finishing the timber elements to the desired dimensions of 200 mm × 240 mm × 200 mm (width × height × length), the samples were conditioned at a temperature of 20 ± 2 °C and a relative humidity of $65 \pm 5\%$ to an average moisture content of $\omega \approx 12\%$. The average sample density $\rho_{\rm m}$ was 362 ± 14 kg/m³. For the purpose of image capturing, the samples were cut into two halves, clamped together with screw clamps, and the self-tapping screws were inserted in the center of the samples without drilling pilot holes. Before performing the pull-out experiments, one half was removed carefully so that the screw was exposed, as shown in Fig. 1.



Fig. 1. (a) Illustration of the specimen RL including the investigated field of views (FoV-1= 40 mm × 70 mm and FoV-2 = 100 mm × 125 mm) and (b) finite-element model of the specimen

In total, three different configurations were tested, *i.e.*, screw insertion in wood grain direction and perpendicular to the wood grain direction with a field of view (*FoV-1* and *FoV-2*) on the specimen surface planes longitudinal-radial (LR), radial-longitudinal (RL), and tangential-radial (TR), as illustrated in Fig. 1a. In order to improve the measurement capability, the surface of the screw of the specimen LR was carefully sanded (heat development was avoided) so that it had the same level as the timber element. With this additional procedure it was assumed that more accurate measurements could be performed because the surface of the specimen was flat. Due to the complexity of this procedure and no further improved measurement results, this procedure was not applied on the other specimens. For the numerical simulation, a finite element model was designed (Fig. 1b) and evaluated with different material properties (cf. section: "Description of the simulation model").

Self-tapping screws

The partially threaded self-tapping screw: "ASSY (Adolf Würth GmbH and Co. KG, Künzelsau, Germany)" with a (nominal) outer thread diameter of d = 12 mm and a (nominal) inner thread diameter of $d_1 = 7.2$ mm was used for the experiments. The complete thread length of $l_g = 130$ mm was inserted into the timber, so that it was feasible to investigate a large timber-screw interface. According to the technical approval ETA-11/0190 (ETA-11/0190 2013), the screw has a characteristic tensile capacity of $f_{\text{tens},k} = 45$ kN, a yield moment of $M_{y,k} = 58$ Nm, and a modulus of elasticity of $E_s = 210$ GPa.

Methods

Experimental set-up

The pull-out experiments (Fig. 2) were performed on the universal testing machine Zwick/Roell Z100 (Zwick GmbH & Co. KG, Ulm, Germany), equipped with a 100 kN load cell and the control software Zwick/Roell testXpert II V3.5 (Zwick GmbH & Co. KG, Ulm, Germany).



Fig. 2. Test set-up of the screw pull-out experiments

The specimens were clamped between a steel beam and the testing machine, so that pulling the screw occurred without any movement of the timber member. Due to the appearing tensile forces, the timber member was pressed against the steel beam and the screw was pulled-out. To ensure that the test occurred in the elastic phase, the maximum applied load was 20% of the theoretical characteristic withdrawal capacity $F_{ax, \alpha, Rk}^{exp}$. The withdrawal capacity was calculated using Eurocode 5 of EN 1995-1-1 (2015), which is shown below,

$$F_{\text{ax, } \alpha, \text{ RK}}^{\text{exp}} = F_{\text{ax, } \alpha, \text{ Rk}} / 2 \tag{1}$$

$$F_{\text{ax, }\alpha, \text{Rk}} = (n_{\text{ef}} \times f_{\text{ax,k}} \times d \times l_{\text{ef}} \times k_{\text{d}}) / (1.2 \times \cos^2(\alpha) + \sin^2(\alpha))$$
(2)

$$f_{\rm ax,k} = 0.52 \times d^{-0.5} \times l_{\rm ef}^{-0.1} \times \rho_{\rm k}^{-0.8} \tag{3}$$

$$k_{\rm d} = \min \left\{ \frac{d/8}{1} \right. \tag{4}$$

where $n_{\rm ef}$ is the effective number of used screws. The $f_{\rm ax, k}$ is the characteristic value of the withdrawal strength, which depends on the outer thread diameter d (mm), the penetration length of threaded part $l_{\rm ef}$ (in this case $l_{\rm ef} = l_{\rm g}$), and the characteristic density $\rho_{\rm k} = 347$ kg/m³, which is the 5% percentile of $\rho_{\rm m}$ of the timber. The $k_{\rm d}$ describes a reduction factor that must be applied for screws with an outer thread diameter of $d \le 8$ mm. The angle of the screw axis to grain direction is also needed and defined by the parameter α , which were either 0° or 90°. The experimental tests were conducted at a crosshead speed of 5 mm/min. Further, applying low forces indicated that the out-of-plane motion was expected to be low enough to be negligible. Pre-tests and simulations also confirmed that assumption.

Specimen	Load per Load Step: "n (-)"	Force per Load Step: " <i>F</i> _n (N)"	Preload: " <i>F</i> √ (N)"	Maximal Force: " <i>F</i> _{max} (N)"	Expected Characteristic Withdrawal Capacity: " <i>F</i> _{ax, α, Rk} ^{exp} (N)"	Ratio of Forces: " <i>F</i> _u / <i>F</i> _{ax, α,} _{Rk} ^{exp} (%)"
LR	10	50	550	1050	6500	16
RL	15	10	1050	1200	7500	16
TR	15	20	1050	1350	7500	18

 Table 1. Experimental Parameters

ESPI technique

The ESPI (Q300 ESPI System; Dantec-Ettemeyer, Ulm, Germany) is a non-contact full-field optical gauging technique, which was used to capture the planar strain distribution around the timber-screw interface. The ESPI provides high-resolution deformations so that the deformation of heterogeneous and anisotropic materials such as wood can be detected (Valla *et al.* 2011; Kumpenza *et al.* 2018). Detailed descriptions with the basic principle of the ESPI technique are given by several authors (Eberhardsteiner 1995, Jones and Wykes 1989; Gingerl 1998; Schmidt *et al.* 2003; Martinez *et al.* 2004; Müller *et al.* 2005; Hagara *et al.* 2016). In short, for in-plane measurements (movements in x- and z-axis) the sample surface is illuminated from two different planar directions with a laser beam, and the superposition of both reflected light waves forms a speckle pattern (resulting interference distribution), which is registered by a CCD camera as illustrated in Fig. 3.



Fig. 3. ESPI set-up for in-plane measurements (schematic drawing based on Müller et al. 2005)

The intensity distribution of the speckle pattern image can be described with the following equation,

$$I_{(\mathbf{u},\mathbf{v})} = I_{\mathcal{O}(\mathbf{u},\mathbf{v})} \times \left[1 + \gamma_{(\mathbf{u},\mathbf{v})} \times \cos(\phi_{(\mathbf{u},\mathbf{v})})\right]$$
(5)

where $_{(u,v)}$ were the coordinates on the CCD chip, I_0 is the intensity of the laser beam, γ described the contrast function and ϕ the phase of the laser beam front. Surface movements caused by mechanical loading led to new phase differences between the reflected light waves and thus to new speckle pattern images, which were stored by a computer. Subtracting the upcoming speckle pattern image from the initially captured image gives rise to an image with typical fringe pattern, in which points along the fringes correspond to lines of constant displacement in the direction of the defined sensitivity vector (Müller *et al.* 2005). This image with a typical fringe pattern was transformed into a map of displacement after applying a temporary phase-shift method (An and Carlsson 2003). Finally, through post-processing, a map of strain distribution was derived. One to ten fringes had been proved to be appropriate for ESPI measurements, which means that for higher loads the experiment has to be divided into several load steps (Müller *et al.* 2015).

Strain measurement using ESPI

To improve the signal to noise ratio of ESPI measurements, the investigated specimen surface was colored with a matt white spray paint (Werkstoffprüfung HÖDL GmbH, Wels, Austria) before the screw pull-out tests were conducted. The ESPI focus was adjusted on the screw axis. Depending on the specimen, different maximal load forces (F_{max}) were calculated using Eqs. (1 to 4). The maximum load (F_{max}) was applied step-by-step in each pull-out test, so that image capturing could be performed correctly. In addition, special care had to be taken to guarantee that the timber elements had no movements at all during image capturing. This was because additional movements in the specimens can affect ESPI measurements. In this case, the crosshead movement of the universal testing machine was stopped for 5 s at every load step, while the image was captured. The load steps were chosen based on a preliminary study that showed that the induced fringes would give exploitable deformation images, which is needed to calculate consistent strain maps. The total specimen deformation within the field of view (*FoV-1* and *FoV-2*) was established by adding up the images of each load step using the ESPI software ISTRA 2001 (Dantec-Ettemeyer, Ulm, Germany). Afterwards, the in-plane strains, *i.e.*, axial strain (ε_y),

transverse strain (ε_x), and shear strain (γ_{xy}), were calculated by differentiating the deformation images in the horizontal and vertical directions as described in Müller *et al.* (2015). Due to the high sensitivity of ESPI devices, it was necessary to mount the device with an additional supporting frame on the universal testing machine in a way that no lateral movements or vibrations of the device were possible. In addition, a preload (F_v) was always applied before starting the pull-out experiments to stabilize the specimens. The device Q300 (Dantec-Ettemeyer, Ulm, Germany) provided a maximal measurement resolution of 0.03 µm (Dantec Dynamics A/S 2017), which was necessary to capture precise close-up images within the chosen field of view of $FoV-1 = 40 \text{ mm} \times 70 \text{ mm}$ and $FoV-2 = 100 \text{ mm} \times 125 \text{ mm}$ (width × height)

Description of the simulation model

A three-dimensional finite element model (3D-FE) of the test samples (Fig. 1b) was designed and developed with Nastran In-CAD V.2019.2 (Autodesk, Mill Valley, CA, USA). Timber was modelled as a solid orthotropic material (MAT12) with linear-elastic material parameters, whilst the screw was assumed as an isotropic material (MAT1). A linear- static analysis was chosen for simulation, which meant that only elastic deformations were considered. Based on the designed experimental set-up, no plastic deformations could occur, and therefore this assumption was made. Various literature (Kollmann 1968; Neuhaus 1981; Keunecke *et al.* 2008; Dahl and Malo 2009; Müller *et al.* 2015; Ringhofer 2017; Niemz and Sonderegger 2017) were considered to find suitable material parameters for the stiffness matrix [C], which includes Young's moduli (E_x , E_y , and E_z), Poisson's ratios (v_{xy} , v_{zx} , and v_{zy}), and shear moduli (G_{xy} , G_{zx} , and G_{zy}). The simulation model parameters are summarized in Table 2.

Specimen	Density (kg/m ³)	Young's Modulus ^a (GPa)			Poisson's Ratio ^a (-)			Shear Modulus⁵ (GPa)			
	ρ	Ex	Ey	Ez	Vху	Vzx	Vzy	G _{xy}	Gzx	Gzy	
LR	349	0.82	0.42	11.9	0.570	0.035	0.055	0.025	0.530	0.580	
RL	381	11.9	0.42	0.82	0.055	0.035	0.570	0.580	0.530	0.025	
TR	355	0.82	11.9	0.42	0.035	0.570	0.055	0.530	0.025	0.580	
Source:	^a Neuhaus (1981); ^b Ringhofer (2017)										

Table 2. Simulation Model Parameters

Depending on the investigated test configuration (LR, RL, or TR), the coordinate system of the specimen was rearranged to simulate the corresponding timber orientation. The contact condition between timber and screw was set to "separation", so that sliding as well as the opening was possible. Analogous to the experiments (Fig. 2), the upper surface of the specimen was constrained in all six directions for translation (T_x , T_y , and T_z) and rotation (R_x , R_y , and R_z). For the simulations, the preload (F_v) and the maximal load (F_{max}) were applied in a single step. The forces were applied at the borderline between the screw head and shaft in the global z-direction. The mesh was generated using the automatic mesh generator included in Nastran In-CAD V.2019.2 software (Autodesk, Mill Valley, CA, USA). General mesh size for the specimen was 8 mm and 4 mm for the screw. The maximum element growth rate was set to 1.25 mm and element shape was set to tetrahedron. Additionally, three different mesh controls were applied. The first mesh control (1-mm element size) was applied on the surface of the specimen, covering the area

from the screw shaft 11.4 mm outwards and over the whole screw length downwards. The second mesh control (0.3 mm) was used to approximate the mesh size at the threads between the screw and the specimen. The third mesh control (1.5 mm) was applied to the specimen at the interphase between the screw shaft and specimen borehole. The general aim of the model was to replicate the deformations obtained through laboratory tests. This should provide further insights into the plausibility of the laboratory results.

RESULTS AND DISCUSSIONS

Figure 4 shows an overview of all established in-plane strains, *i.e.*, axial strain (ε_v) , transverse strain (ε_x), and shear strain (γ_{xy}), within the chosen field of view of FoV-1 = 40 mm \times 70 mm across the timber-screw interface. For each test configuration (cf. Tables 1 and 2) the ESPI and FEM results are presented in false colors (colors that differ from the natural color impression). The displayed false colors describe the full-field strain distribution, whereby the red color represents a positive strain value and dark blue a negative strain value. Due to the use of false colors, fine deviations are clearly distinguishable. Independent of the specimen, a characteristic strain distribution was obtained for all three strain maps, which also reflected the specific geometry of the timberscrew interface. As expected, at the interface, strain concentrations were detected for all three strain components. The relatively low stiffness of spruce wood, *i.e.*, modulus of elasticity of $E_{\rm L} = 10$ to 14 GPa, $E_{\rm R} = 0.6$ to 1 GPa, and $E_{\rm T} = 0.4$ to 0.5 GPa in the longitudinal, radial, and tangential directions, respectively, compared to the stiffness of the screw of $E_{\rm S} = 210$ GPa, leads to compression and expansion of the wood material in the range of -5% to +5 %. In the axial direction, the strain concentrations (ε_v) around the screw thread were alternating from negative to positive values over the complete screw length (Fig. 4a, 4b, and 4c). Moreover, the axial strains (ε_v) have an "arch-shaped" form that was influenced by the thread geometry of the inserted screws. Compression and expansion of the wood material appeared mainly above and beneath the thread flanks, which led directly to the pronounced local axial strain concentrations around the screw-thread. Applying ESPI for the strain measurement has enabled the visualization and measurement of this phenomenon.

Even though the applied forces differed between the configurations, a higher intensity of the axial strain (ε_y) for the specimen with screw insertion perpendicular to the wood grain direction (Fig. 4b and 4c) compared to the specimen with screw insertion in the wood grain direction (Fig. 4a) can be observed. High material stiffness ($E_L > E_R$ and $E_L > E_T$) means low capacity of material deformation, but at the same time high capability of stress transmission, which could also explain the relatively high stresses that can be transmitted in the axial direction for the specimen LR ($E_z = E_L$) and in transverse direction for the specimen RL ($E_x = E_L$). Regarding the transverse strain (ε_x), a high concentration at the screw insertion point was observed that decreased dramatically until the screw tip was reached (Fig. 4d, 4e, and 4f). Compared to that, the shear strains (Fig. 4g, 4h, and 4i) were nearly evenly distributed over the screw penetration length.

The FEM results illustrated that on a qualitative level, the simulation depicted the results of the pull-out experiments quite well (Fig. 4), which also confirmed that ESPI was suitable to capture the micro mechanical deformations. However, the quantitative validation of the experiments with the simulations showed that they were partly deviations in the simulated results, in comparison with the experimental observations. Several reasons

might lead to these deviations. For example, the simulation model did not consider material densification and damages that were caused due to inserting the screw into the timber. Especially in the vicinity of the screw, these changes in the timber material would have an influence on the strain behavior during the pull-out tests. Furthermore, compared to the simulations, the strains derived from the experiments did not follow the same calculation principle. On the one hand the strains were derived from highly accurate and sensitive deformation measurements, and in the other hand, there were numerical calculations that were dependent on the applied material model and properties (based on Hooke's law). Small continuation errors occurred in the calculation because the literature values were used for the material models (MAT1, MAT12) that could have led to these deviations. Another influencing factor could be the element-size of the simulation model, which exceeded the occurring deformations at the mechanical timber-screw interface. Using smaller elements would lead to high computing time.



Fig. 4. ESPI and FEM strain maps (\mathcal{E}_{y} , \mathcal{E}_{x} , and \mathcal{I}_{xy}) within the observed field of view of $FoV-1 = 40 \text{ mm} \times 70 \text{ mm}$ of the specimens LR, RL, and TR

To better understand the mechanics along the interface section, minimal and maximal strains ($\varepsilon_v^{\min(LR)}$, $\varepsilon_v^{\max(LR)}$, $\varepsilon_x^{\min(LR)}$, $\varepsilon_x^{\max(LR)}$, $\gamma_{xv}^{\min(LR)}$, and $\gamma_{xv}^{\max(LR)}$) of the specimen LR were plotted over the penetration length (l_p) of the inserted screw (Fig. 5). All strains showed a curve progression that had at the screw insertion point the highest amplitudes that decreased over the penetration length. Ellingsbø and Malo (2012) and Trautz (2017) also reported an inhomogeneous stress-strain distribution over the screw length with a maximum at the screw insertion point, even though the timber-screw interface was not investigated. Moreover, it must be taken into account that applying full-field optical gauging techniques like DIC and ESPI always means that the object surface is described as a speckle pattern image that is subsequently used to create a map of deformation of the investigated surface (Jones and Wykes 1989; Zink et al. 1995). Consequently, investigating a surface that was far away from the stressed volume led to a noticeable underestimation of the true expected deformations and strains. Thus, regarding the results established in Ellingsbø and Malo (2012), Ayoubi and Trautz (2015), Ayoubi (2014), and Trautz (2017), this effect has to be considered, especially when there is a need to make a statement about the upcoming strain-stress distributions at the mechanical timber-screw interface.



Fig. 5. Progression of the minimal and maximal strains (\mathcal{E}_y , \mathcal{E}_x , and \mathcal{P}_{xy}) over the penetration length of the specimen LR within the field of view of $FoV-2 = 100 \text{ mm} \times 125 \text{ mm}$

Looking at the transverse strain (ε_x) and shear strain (γ_{xy}) it is also important to identify the affected region in the wood, because the interaction of transverse and shear stresses is the major reason for failure in the timber-screw connection. For example, the timber material edge or a second screw axis is placed close to the screw, stresses cannot subside into the surrounding material completely, and the calculated load-carrying capacity might not be achieved. The specimen LR showed a high strained region with a total width of w (LR) = 22 mm, RL a region with a total width of w (RL) = 19 mm, and for TR a region with a total width of w (TR) = 18 mm. The captured regions were far below the design recommendations of Eurocode 5, which said that from the screw axis to the timber edge, there should be a minimum distance of $a_{1, CG} = 10 \times d$ (= 120 mm) for screws inserted in the wood grain direction or rather $a_{2,CG} = 4 \times d$ (= 48 mm) for screws inserted perpendicular

to the wood grain direction. The minimum distance from screw axis to screw axis is defined in Eurocode 5 with $a_1 = 7 \times d$ (= 84 mm) and $a_2 = 5 \times d$ (= 60 mm) in the wood grain direction and perpendicular to the wood grain direction, respectively. In this context, it must be mentioned that the recommended screw distances in Eurocode 5 also considered splitting effects that can occur while the self-tapping screws were inserted (no pilot holes) into the timber material. Therefore, a direct comparison of the screw distances (a_1 , a_2 , a_1 _{CG}, and a_2 _{CG}) to the measured values (w (LR), w (RL), w (TR)) was possible only to a limited extent, because in this study the affected wood material region in consequence of screw pull-out was analyzed without observing the screw insertion mechanisms.

The observation of the strain maps of the simulation underlined the necessity to use correct and accurate elastic material parameters ([C]) to establish precise results, especially in the vicinity of the screw. In this study, these elastic material parameters ([C]) were taken from literature corresponding to the measured average specimen density $\rho_{\rm m}$, as there is a known correlation between elastic wood material properties and wood density (Gibson et al. 1995). Using these values from the literature for the simulation can only be a first approach to estimate the strains and further the stresses along the mechanical interface "timber-screw". Even though the elastic material parameters ([C]) were chosen corresponding to the measured specimen density $\rho_{\rm m}$, there was a damaged and densified region especially at the interface section "timber-to-screw". Therefore, the real elastic material parameters at the interface section might be remarkably different to the ones given in the literature. Thus, using values from the literature meant approximating the simulation results and the stresses in the experiments. This phenomenon can only be avoided if density measurement was performed at the mechanical timber-screw interface section. The next step would be to select the elastic material parameters ([C]) corresponding to the "interfacesection" density. The more accurate approach would be applying into complex testing procedures to establish the elastic material parameters ([C]) at the interface directly without using literature values at all.

However, the strain maps determined in this study showed where the strain concentrations were localized, which curve progression can be expected, and what wood material region was affected during pull-out tests. Finally, the potential to use ESPI as direct optical strain measurement technique to understand the mechanical interactions along the interface section "timber-screw" was also proved. The hypothesis that high resolution full-field optical gauging techniques like ESPI can give insights into the strain and therefore at the timber-screw interface, was confirmed. For better simulation performance and even profound calculation of the stress distribution, density measurement across the interface section "timber-screw" was suggested, so that more accurate elastic material parameters can be selected and applied. In general, for further validation of the strain distribution, further FEM simulation should be conducted.

CONCLUSIONS

1. This study has shown that ESPI was capable of localizing, visualizing, and accurately measuring the strain distribution along the mechanical timber-screw interface, which did not exceed values higher than $|\pm 5|$ ‰. Furthermore, it was clarified that the screw-thread geometry determined the location and the shape of the expected strain concentrations (ε_y , ε_x , and γ_{xy}).

- 2. A good qualitative correlation was found between the finite element simulation and the experiments. However, on a quantitative level, the simulation results partly differed from the experimental results. The reasons for these deviations might be for example, the applied material model and properties, which needed to be approximated.
- 3. It has been shown that high strain concentrations at the screw insertion point can be expected, which decreased over the screw penetration length (l_p) when the screw was tested in withdrawal. Thus, it was assumed that not all screw-threads contributed equally to the withdrawal capacity of the observed "timber-screw" specimens.
- 4. The affected wood material regions were smaller compared to the wood material regions that were defined in Eurocode 5.

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